

# Symmetry in electromagnetism: group theory and Maxwell's equations

Simon Horsley



## Part 1: A sketch of group theory

# Symmetry: nature, art, and physics



Rotational symmetry



Reflection symmetry

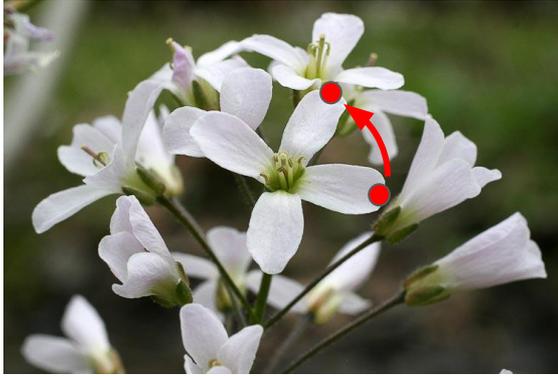


Translational symmetry

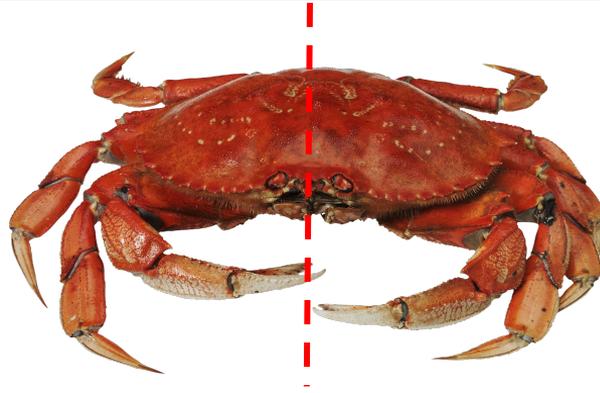


Permutation symmetry

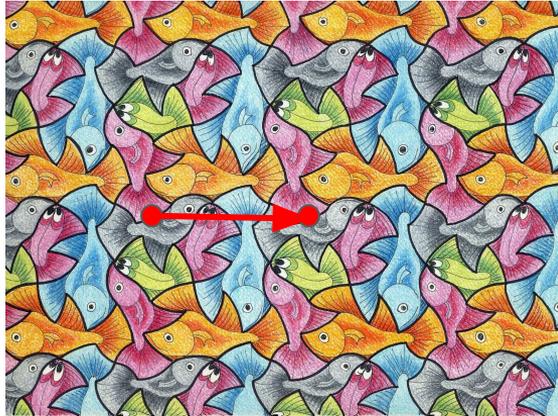
# Symmetry: nature, art, and physics



Rotational symmetry



Reflection symmetry



Translational symmetry



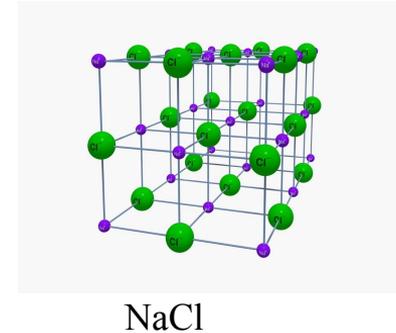
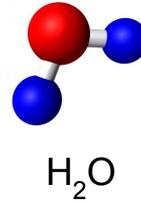
Permutation symmetry

# Symmetry: nature, art, and physics

## Symmetry in physics:

- Discrete rotation and translation symmetry of atoms molecules and crystals. (Quantum chemistry)
- Time and space inversion symmetry (e.g. Newton's equations).
- Electric/magnetic duality symmetry (two polarization of EM waves).
- Continuous translation and rotation symmetry (Conservation laws).
- Local continuous gauge symmetry and diffeomorphism invariance (Standard Model and General Relativity)

## Symmetries of matter

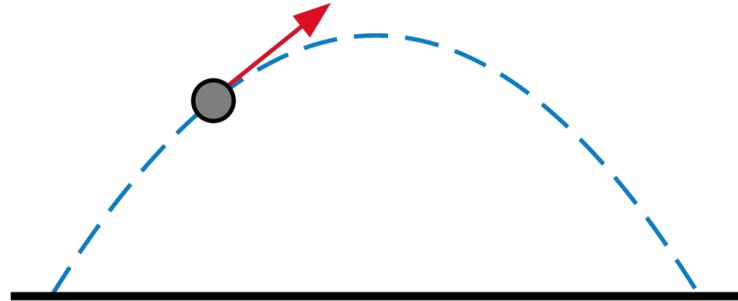


# Symmetry: nature, art, and physics

## Symmetry in physics:

- Discrete rotation and translation symmetry of atoms molecules and crystals. (Quantum chemistry)
- Time and space inversion symmetry (e.g. Newton's equations).
- Electric/magnetic duality symmetry (two polarization of EM waves).
- Continuous translation and rotation symmetry (Conservation laws).
- Local continuous gauge symmetry and diffeomorphism invariance (Standard Model and General Relativity)

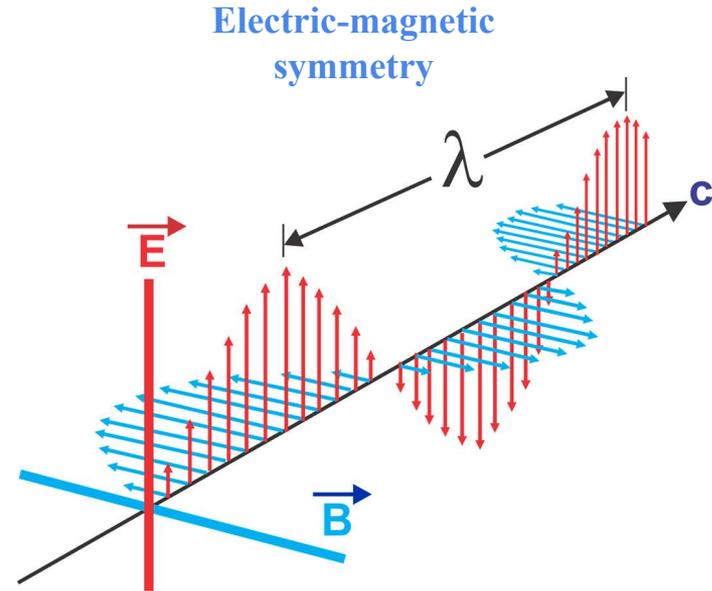
## Time symmetric motion



# Symmetry: nature, art, and physics

## Symmetry in physics:

- Discrete rotation and translation symmetry of atoms molecules and crystals. (Quantum chemistry)
- Time and space inversion symmetry (e.g. Newton's equations).
- Electric/magnetic duality symmetry (two polarization of EM waves).
- Continuous translation and rotation symmetry (Conservation laws).
- Local continuous gauge symmetry and diffeomorphism invariance (Standard Model and General Relativity)



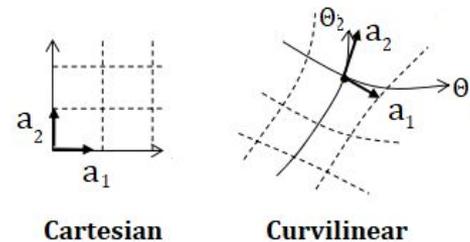
# Symmetry: nature, art, and physics

## Symmetry in physics:

- Discrete rotation and translation symmetry of atoms molecules and crystals. (Quantum chemistry)
- Time and space inversion symmetry (e.g. Newton's equations).
- Electric/magnetic duality symmetry (two polarization of EM waves).
- Continuous translation and rotation symmetry (Conservation laws).
- Local continuous gauge symmetry and diffeomorphism invariance (Standard Model and General Relativity)

## Gauge theory and general covariance

The diagram illustrates a gauge transformation. On the left, a red wave represents the vector potential  $A_x$ . A blue arrow points to the right, where a blue wave represents the transformed vector potential  $A_x - \frac{e}{\hbar} \partial_x \phi$ . To the right of the blue wave is the phase factor  $\times e^{i\phi(x)}$ .



$$R^\mu_\nu - \frac{1}{2} R \delta^\mu_\nu = \frac{8\pi G}{c^4} T^\mu_\nu$$

# How to describe symmetry



# How to describe symmetry

**Image as a vector:**  $|\psi\rangle = \begin{pmatrix} p_0 \\ p_1 \\ p_2 \\ \dots \\ p_N \end{pmatrix}$

Split image up into  $N$  pixels



# How to describe symmetry

**Image as a vector:**  $|\psi\rangle = \begin{pmatrix} p_0 \\ p_1 \\ p_2 \\ \dots \\ p_N \end{pmatrix}$

**Transformed image:**  $|\psi'\rangle = \hat{M}|\psi\rangle = \begin{pmatrix} p'_0 \\ p'_1 \\ p'_2 \\ \dots \\ p'_N \end{pmatrix}$

Split image up into  $N$  pixels



A symmetry *group* is the collection of *all* the matrices  $M$  that leave the object unchanged.

**Symmetry if:**  $|\psi'\rangle = |\psi\rangle$

# How to describe symmetry

**Image as a vector:**  $|\psi\rangle = \begin{pmatrix} p_0 \\ p_1 \\ p_2 \\ \dots \\ p_N \end{pmatrix}$

**Simpler example:**

$p_0$	$p_1$
$p_2$	$p_3$

**Transformed image:**  $|\psi'\rangle = \hat{M}|\psi\rangle = \begin{pmatrix} p'_0 \\ p'_1 \\ p'_2 \\ \dots \\ p'_N \end{pmatrix}$

**Symmetry if:**  $|\psi'\rangle = |\psi\rangle$

# Group theory

## What is a 'group'?

1. *Associative multiplication  $A(BC) = (AB)C$*
2. *Closure (you can't get something not in the group from combining elements)*
3. *Inverse (for every  $A$  there is an  $A^{-1}$  such that  $A^{-1}A = E$ )*
4. *Identity (the group contains the identity  $E$ )*



A group is a  
'bag' of matrices

# Group theory

## What is a 'group'?

1. *Associative multiplication  $A(BC) = (AB)C$*
2. *Closure (you can't get something not in the group from combining elements)*
3. *Inverse (for every  $A$  there is an  $A^{-1}$  such that  $A^{-1}A = E$ )*
4. *Identity (the group contains the identity  $E$ )*

**Proof that we have a group in our example:**



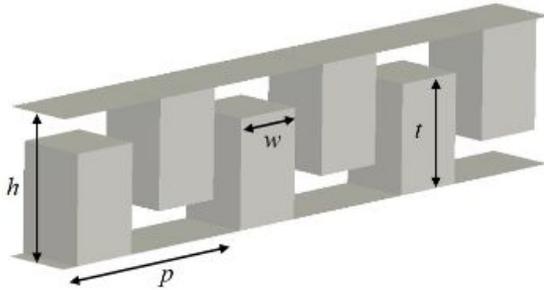
A group is a  
'bag' of matrices

# Group theory

Example - higher symmetry waveguide:

Symmetry group elements:

a.



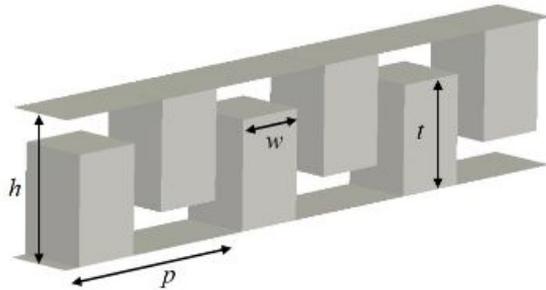
O. Quevedo-Teruel, G. Valerio, Z. Sipus, and E. Rajo-Iglesias, “*Periodic structures with higher symmetries and their applications in electromagnetic devices*” IEEE Microwave Magazine (2020)

# Group theory

Example - higher symmetry waveguide:

Symmetry group elements:

a.



O. Quevedo-Teruel, G. Valerio, Z. Sipus, and E. Rajo-Iglesias, “*Periodic structures with higher symmetries and their applications in electromagnetic devices*” IEEE Microwave Magazine (2020)

This is a so-called ‘*Frieze group*’, denoted  $p11g$ . See e.g. Conway et. al. “*The symmetries of things*”

# Group theory

More complicated glide symmetry:

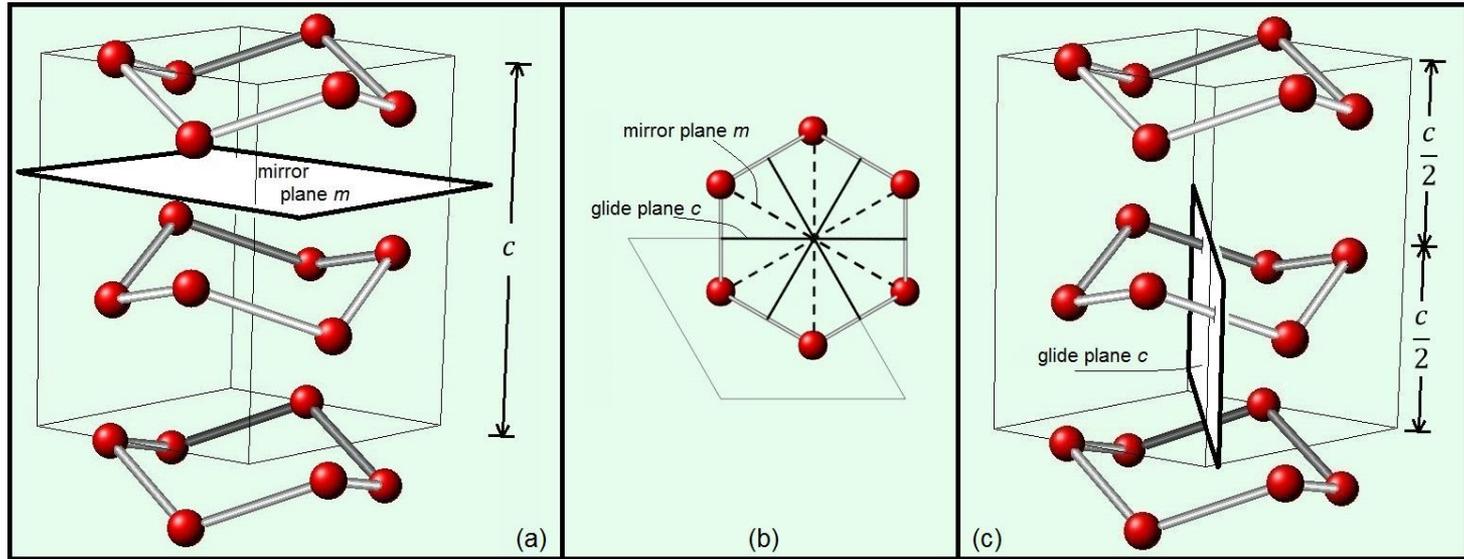
“Hexagonal Ice”  $\text{H}_2\text{O}$



# Group theory

More complicated glide symmetry:

“Hexagonal Ice”  $\text{H}_2\text{O}$



Has combinations of rotation, mirror plane, and translation symmetry operations. Characterized by one (called  $P6_3/mmm$ ) of the 230 possible “*space groups*”.

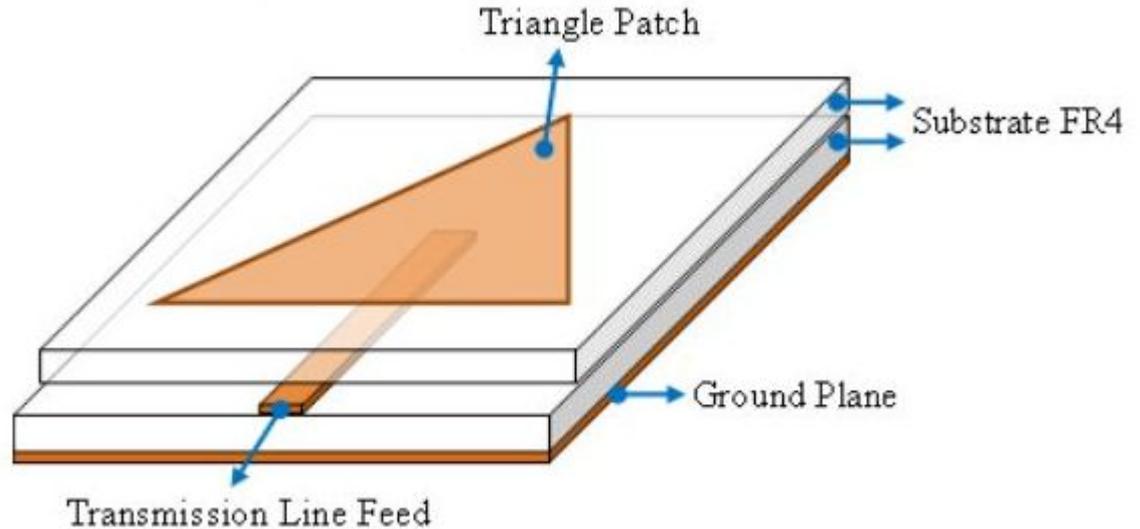
(See e.g. <http://img.chem.ucl.ac.uk/sgp/>)

# Representations of groups

There are many '*isomorphic*' collections of symmetry group matrices. The same group structure can be realised in many different ways.

**Example: C<sub>3</sub> group (3 fold rotation)**

<b>C<sub>3</sub></b>	<b>M</b>	<b>M<sup>2</sup></b>	<b>E</b>
<b>M</b>	<b>M<sup>2</sup></b>	<b>E</b>	<b>M</b>
<b>M<sup>2</sup></b>	<b>E</b>	<b>M</b>	<b>M<sup>2</sup></b>
<b>E</b>	<b>M</b>	<b>M<sup>2</sup></b>	<b>E</b>



# Representations of groups

There are many '*isomorphic*' collections of symmetry group matrices. The same group structure can be realised in many different ways.

**Example: C3 group (3 fold rotation)**

**Representation 1:**  $M = e^{2\pi i/3}$

<b>C3</b>	<b>M</b>	<b>M<sup>2</sup></b>	<b>E</b>
<b>M</b>	<b>M<sup>2</sup></b>	<b>E</b>	<b>M</b>
<b>M<sup>2</sup></b>	<b>E</b>	<b>M</b>	<b>M<sup>2</sup></b>
<b>E</b>	<b>M</b>	<b>M<sup>2</sup></b>	<b>E</b>

# Representations of groups

There are many '*isomorphic*' collections of symmetry group matrices. The same group structure can be realised in many different ways.

**Example: C3 group (3 fold rotation)**

**Representation 1:**  $M = e^{2\pi i/3}$

<b>C3</b>	<b>M</b>	<b>M<sup>2</sup></b>	<b>E</b>
<b>M</b>	<b>M<sup>2</sup></b>	<b>E</b>	<b>M</b>
<b>M<sup>2</sup></b>	<b>E</b>	<b>M</b>	<b>M<sup>2</sup></b>
<b>E</b>	<b>M</b>	<b>M<sup>2</sup></b>	<b>E</b>

**Representation 2:**  $M = \begin{pmatrix} \frac{1}{2} & \frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & \frac{1}{2} \end{pmatrix}$

# Representations of groups

There are many '*isomorphic*' collections of symmetry group matrices. The same group structure can be realised in many different ways.

**Example: C<sub>3</sub> group (3 fold rotation)**

<b>C<sub>3</sub></b>	<b>M</b>	<b>M<sup>2</sup></b>	<b>E</b>
<b>M</b>	<b>M<sup>2</sup></b>	<b>E</b>	<b>M</b>
<b>M<sup>2</sup></b>	<b>E</b>	<b>M</b>	<b>M<sup>2</sup></b>
<b>E</b>	<b>M</b>	<b>M<sup>2</sup></b>	<b>E</b>

**Representation 1:**  $M = e^{2\pi i/3}$

**Representation 2:**  $M = \begin{pmatrix} \frac{1}{2} & \frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & \frac{1}{2} \end{pmatrix}$

**Representation 3:**  $M = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2} & \frac{\sqrt{3}}{2} \\ 0 & -\frac{\sqrt{3}}{2} & \frac{1}{2} \end{pmatrix}$

# Representations of groups

There are many '*isomorphic*' collections of symmetry group matrices. The same group structure can be realised in many different ways.

**Example: C<sub>3</sub> group (3 fold rotation)**

<b>C<sub>3</sub></b>	<b>M</b>	<b>M<sup>2</sup></b>	<b>E</b>
<b>M</b>	<b>M<sup>2</sup></b>	<b>E</b>	<b>M</b>
<b>M<sup>2</sup></b>	<b>E</b>	<b>M</b>	<b>M<sup>2</sup></b>
<b>E</b>	<b>M</b>	<b>M<sup>2</sup></b>	<b>E</b>

**Representation 1:**  $M = e^{2\pi i/3}$

**Representation 2:**  $M = \begin{pmatrix} \frac{1}{2} & \frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & \frac{1}{2} \end{pmatrix}$

**Representation 3:**  $M = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2} & \frac{\sqrt{3}}{2} \\ 0 & -\frac{\sqrt{3}}{2} & \frac{1}{2} \end{pmatrix}$

...

# Irreducible representations

**Q:** How do we deal with this ambiguity of how to represent the group?

**A:** Find the ‘irreducible representations’.

A representation is fully reducible if, for every matrix in the group we can perform a transformation  $M' = TMT^{-1}$  such that,

$$M = \begin{pmatrix} \mathbf{M}_1 & \mathbf{0} & \dots & \mathbf{0} \\ \mathbf{0} & \mathbf{M}_2 & \dots & \mathbf{0} \\ \dots & \dots & \dots & \mathbf{0} \\ \dots & \dots & \dots & \mathbf{M}_n \end{pmatrix}$$

$n_1 \times n_1$  matrix

$n_2 \times n_2$  matrix

The  $\mathbf{M}_1, \mathbf{M}_2, \dots, \mathbf{M}_n$  are each elements of an irreducible representation of the group. They are the “smallest” matrices that capture the group structure (the symmetry).

# The dimensions of irreducible representations

**A useful theorem:** 
$$\sum_{\mu} n_{\mu}^2 = g$$

See e.g. M. Hamermesh “Group Theory and its application to Physical Problems” (Dover)

# The dimensions of irreducible representations

A useful theorem:  $\sum_{\mu} n_{\mu}^2 = g$

Example: find irreducible representations of  $C_3$  rotation group:

$$M = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2} & \frac{\sqrt{3}}{2} \\ 0 & -\frac{\sqrt{3}}{2} & \frac{1}{2} \end{pmatrix} \quad M^2 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -\frac{1}{2} & \frac{\sqrt{3}}{2} \\ 0 & -\frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix} \quad E = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

# Irreducible representations and degeneracy

The solutions to Maxwell's equations transform as irreducible representations of the relevant symmetry group

Symmetry operator generates a new solution to Maxwell's equations:

$$\hat{M} \begin{pmatrix} \mathbf{E}_n \\ c\mathbf{B}_n \end{pmatrix} = \sum_m M_{nm} \begin{pmatrix} \mathbf{E}_m \\ c\mathbf{B}_m \end{pmatrix}$$

↑  
Symmetry operator (e.g. glide transformation).

# Irreducible representations and degeneracy

The solutions to Maxwell's equations transform as irreducible representations of the relevant symmetry group

Symmetry operator generates a new solution to Maxwell's equations:

$$\hat{M} \begin{pmatrix} \mathbf{E}_n \\ c\mathbf{B}_n \end{pmatrix} = \sum_m M_{nm} \begin{pmatrix} \mathbf{E}_m \\ c\mathbf{B}_m \end{pmatrix}$$

← Solution to Maxwell's equations, for e.g. fixed frequency  $\omega$ .  
One or more degenerate solutions.

# Irreducible representations and degeneracy

The solutions to Maxwell's equations transform as irreducible representations of the relevant symmetry group

Symmetry operator generates a new solution to Maxwell's equations:

$$\hat{M} \begin{pmatrix} \mathbf{E}_n \\ c\mathbf{B}_n \end{pmatrix} = \sum_m M_{nm} \begin{pmatrix} \mathbf{E}_m \\ c\mathbf{B}_m \end{pmatrix}$$

Transformed solution is also a solution to Maxwell's equations, for e.g. fixed frequency  $\omega$ . But it is a different mixture of the degenerate solutions.

# Irreducible representations and degeneracy

The solutions to Maxwell's equations transform as irreducible representations of the relevant symmetry group

Symmetry operator generates a new solution to Maxwell's equations:

$$\hat{M} \begin{pmatrix} \mathbf{E}_n \\ c\mathbf{B}_n \end{pmatrix} = \sum_m M_{nm} \begin{pmatrix} \mathbf{E}_m \\ c\mathbf{B}_m \end{pmatrix}$$

$$\longrightarrow \int d^3 \mathbf{x} (\mathbf{E}_m^*, c\mathbf{B}_m^*) \hat{M} \begin{pmatrix} \mathbf{E}_n \\ c\mathbf{B}_n \end{pmatrix} = M_{nm}$$

The matrices formed from integrals between the symmetry operators and the solutions to Maxwell's equations form an irreducible representation of the symmetry group.

## Example: degeneracy in a triangular waveguide

Maxwell's equations, simplified for the two polarizations:

E polarization:

$$\nabla^2 E_z + (k_0^2 - k_z^2) E_z = 0$$

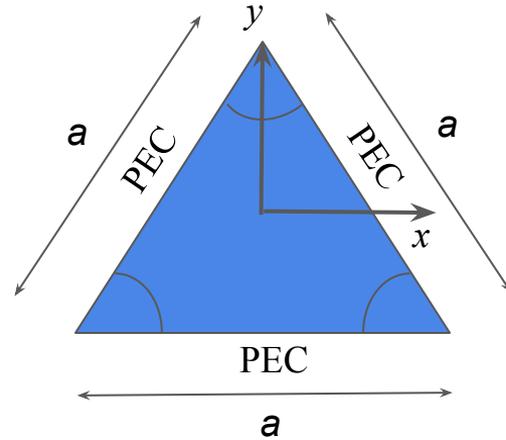
$$E_z = 0 \quad (\text{on PEC boundary})$$

H polarization:

$$\nabla^2 H_z + (k_0^2 - k_z^2) H_z = 0$$

$$\partial H_z / \partial n = 0 \quad (\text{on PEC boundary})$$

After a bit of work we can solve this analytically...



Symmetry group ( $C_{3v}$ , three-fold rotations):

## Example: degeneracy in a triangular waveguide

**Q:** Without solving the equation, what is the degeneracy of the waveguide modes?

**Find the dimension of the irreducible representations of the  $C_{3v}$  group:**

**Our useful theorem:** 
$$\sum_{\mu} n_{\mu}^2 = g$$

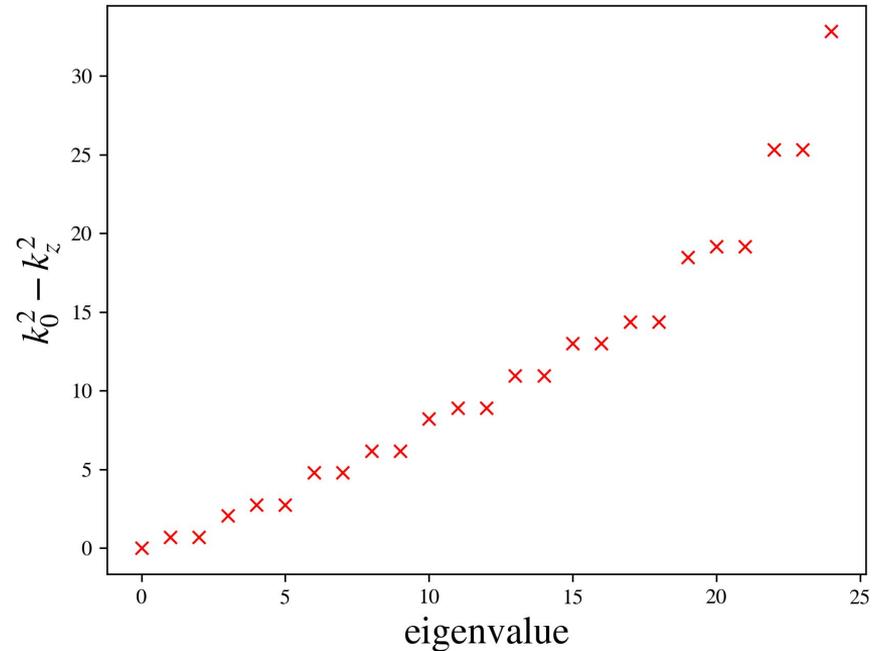
# Example: degeneracy in a triangular waveguide

Exact solutions (quite a bit more work!)

see e.g. B. J. McCartin *SIAM Rev.* 45, 267 (2003)

Exact dispersion relation in triangular waveguide:

$$k_0^2 - k_z^2 = \frac{4}{27} \left( \frac{\pi}{r} \right)^2 [m^2 + n^2 + mn]$$



# Example: degeneracy in a triangular waveguide

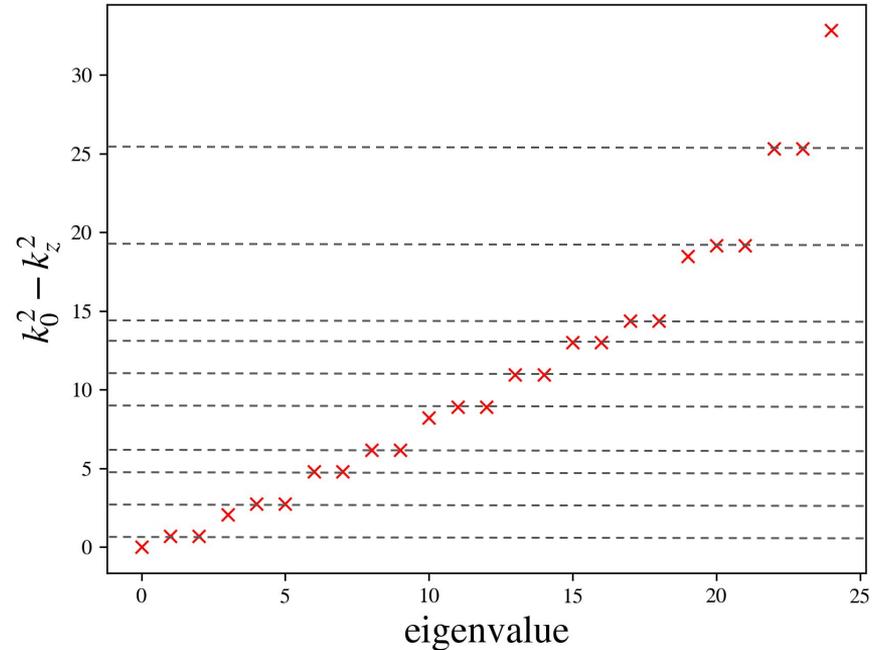
Exact solutions (quite a bit more work!)

see e.g. B. J. McCartin *SIAM Rev.* 45, 267 (2003)

Exact dispersion relation in triangular waveguide:

$$k_0^2 - k_z^2 = \frac{4}{27} \left( \frac{\pi}{r} \right)^2 [m^2 + n^2 + mn]$$

Eigenfunctions of 2 dimensional irreducible representation



# Example: degeneracy in a triangular waveguide

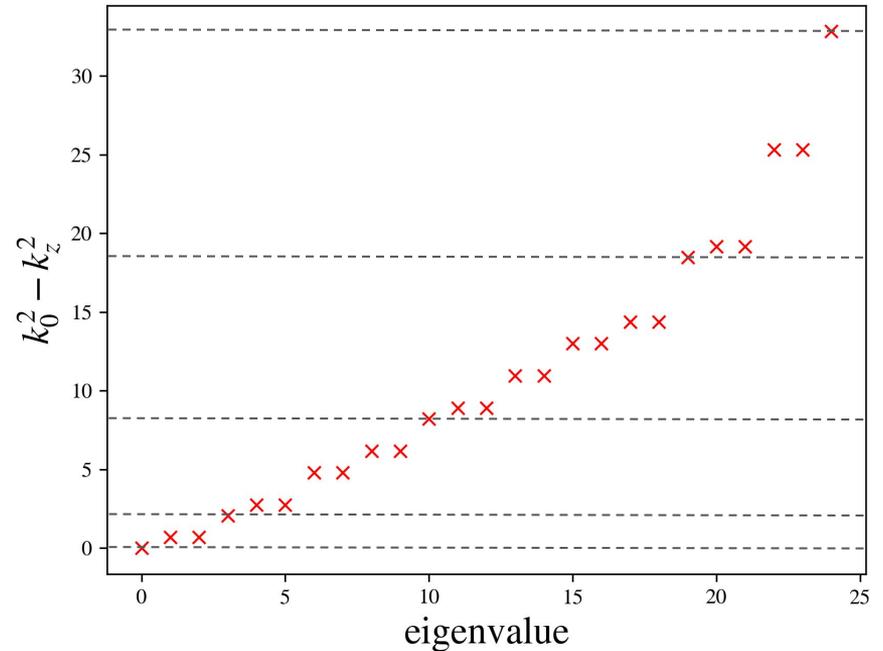
Exact solutions (quite a bit more work!)

see e.g. B. J. McCartin *SIAM Rev.* 45, 267 (2003)

Exact dispersion relation in triangular waveguide:

$$k_0^2 - k_z^2 = \frac{4}{27} \left( \frac{\pi}{r} \right)^2 [m^2 + n^2 + mn]$$

Eigenfunctions of 1 dimensional irreducible representation



5 minute break!

# The story so far...

- Symmetry is an important principle in physics, and can be understood in terms of *symmetry groups*.
- *A group can be thought of as a collection of matrices*, with each matrix corresponding to a transformation of the system (e.g. rotation of coordinates, translation, change of polarization...).
- A group satisfies *four properties*; (1) *associativity of multiplication*; (2) *closure*; (3) every element has an *inverse* in the group; (4) the *identity* matrix is in the group.
- There are many different matrix *representations* of the same group structure.
- The *irreducible representations* are the “smallest” matrix representation of the group, and obey,

$$\sum_{\mu} n_{\mu}^2 = g$$

- The *dimensions of* the matrices forming the *irreducible representations* tell us the possible *degeneracies* of e.g. the frequencies in the system.

## Part 2: Examples of symmetry and group theory in electromagnetic materials

# Translational symmetry and Bloch's theorem

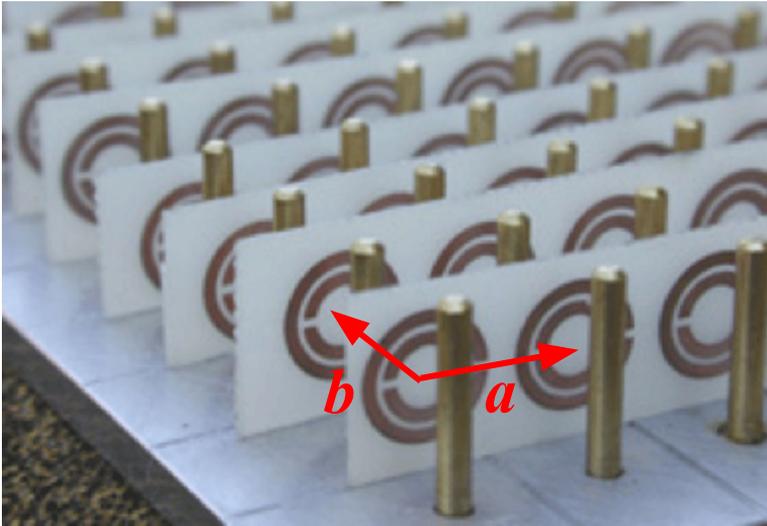


# Translational symmetry and Bloch's theorem

Symmetry transformation of lattice:

$$T_a : \mathbf{x} \rightarrow \mathbf{x} + \mathbf{a}$$

$$T_b : \mathbf{x} \rightarrow \mathbf{x} + \mathbf{b}$$



# Translational symmetry and Bloch's theorem



Symmetry transformation of lattice:

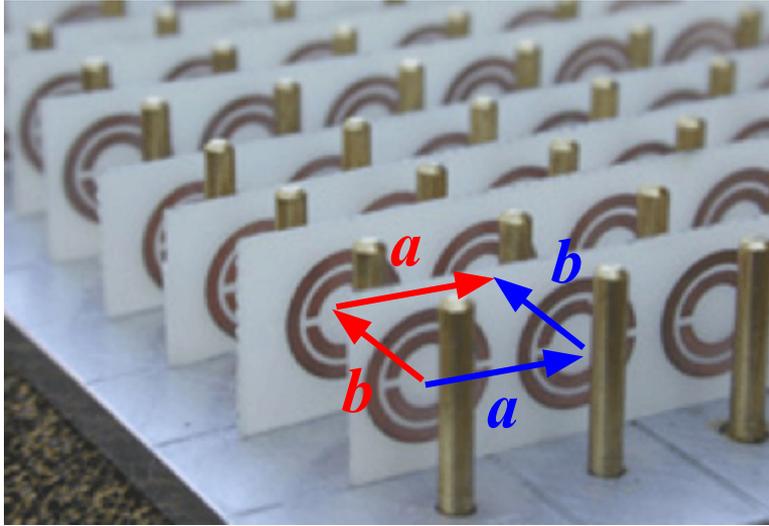
$$T_a : \mathbf{x} \rightarrow \mathbf{x} + \mathbf{a}$$

$$T_b : \mathbf{x} \rightarrow \mathbf{x} + \mathbf{b}$$

Symmetry group contains:

$$(T_b)^n, (T_a)^n$$

# Translational symmetry and Bloch's theorem



Symmetry transformation of lattice:

$$T_a : \mathbf{x} \rightarrow \mathbf{x} + \mathbf{a}$$

$$T_b : \mathbf{x} \rightarrow \mathbf{x} + \mathbf{b}$$

Symmetry group contains:

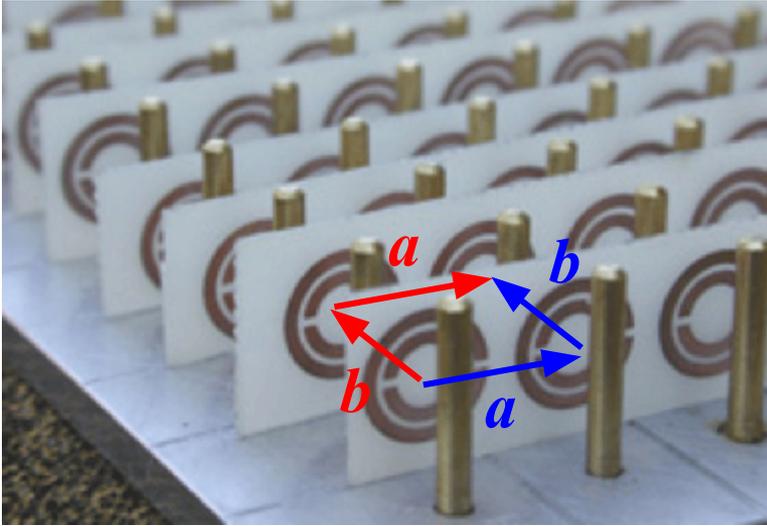
$$(T_b)^n, (T_a)^n$$

All elements commute:

$$[T_a, T_b] = T_a T_b - T_b T_a = 0$$

—————> Matrices can all be simultaneously diagonalized

# Translational symmetry and Bloch's theorem



Symmetry transformation of lattice:

$$T_a : \mathbf{x} \rightarrow \mathbf{x} + \mathbf{a}$$

$$T_b : \mathbf{x} \rightarrow \mathbf{x} + \mathbf{b}$$

Symmetry group contains:

$$(T_b)^n, (T_a)^n$$

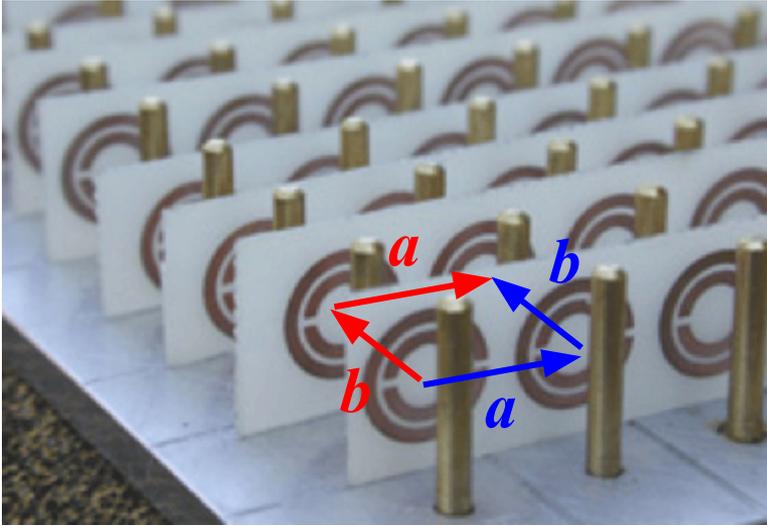
All elements commute:

$$[T_a, T_b] = T_a T_b - T_b T_a = 0$$

—————> Matrices can all be simultaneously diagonalized

—————> Irreducible representations are 1x1

# Translational symmetry and Bloch's theorem



Symmetry transformation of lattice:

$$T_a : \mathbf{x} \rightarrow \mathbf{x} + \mathbf{a}$$

$$T_b : \mathbf{x} \rightarrow \mathbf{x} + \mathbf{b}$$

Symmetry group contains:

$$(T_b)^n, (T_a)^n$$

All elements commute:

$$[T_a, T_b] = T_a T_b - T_b T_a = 0$$

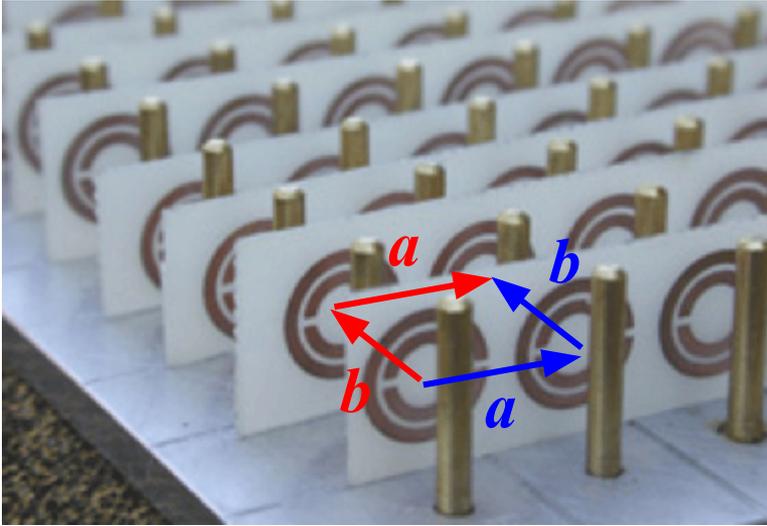
—————> Matrices can all be simultaneously diagonalized

—————> Irreducible representations are 1x1

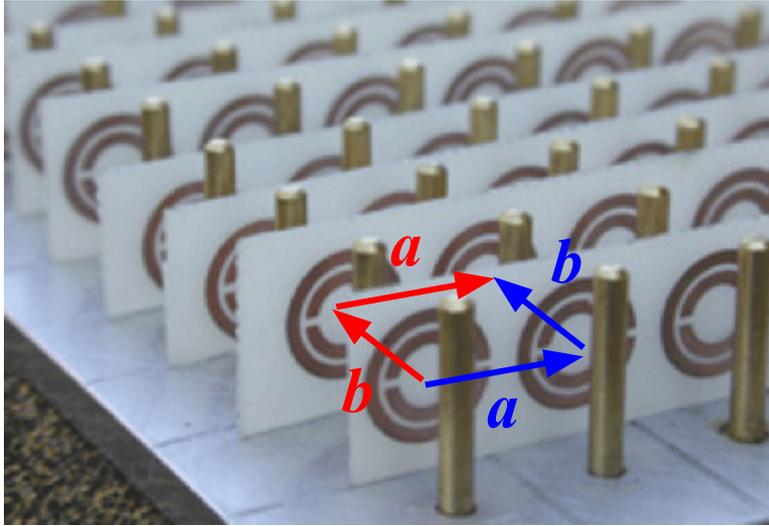
—————> Symmetry transformation is just  $E'_z = cE_z$

# Translational symmetry and Bloch's theorem

Suppose the wave is the same after  $N$  translations along  $\mathbf{a}$ , and  $M$  translations along  $\mathbf{b}$ : i.e.  $T_{\mathbf{a}}^N=1$  and  $T_{\mathbf{b}}^M=1$



# Translational symmetry and Bloch's theorem

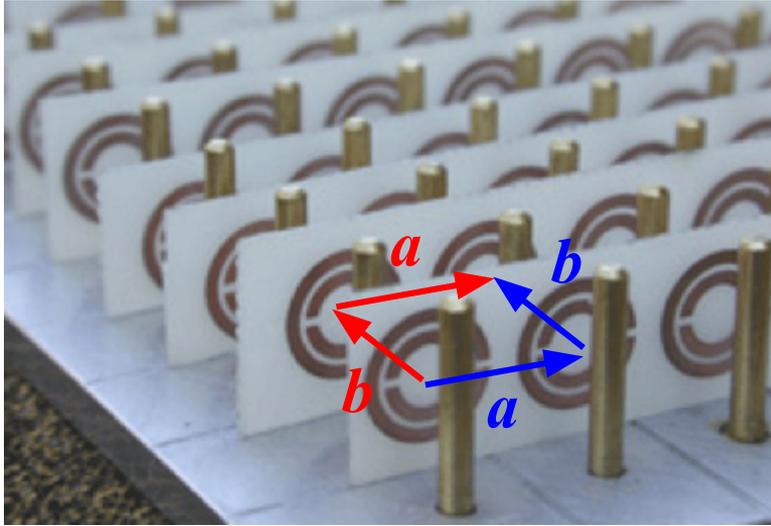


Suppose the wave is the same after  $N$  translations along  $\mathbf{a}$ , and  $M$  translations along  $\mathbf{b}$ : i.e.  $T_{\mathbf{a}}^N=1$  and  $T_{\mathbf{b}}^M=1$

$$\longrightarrow T_{\mathbf{a}} = e^{\frac{2\pi i}{M}} = e^{i\mathbf{K}\cdot\mathbf{a}}$$

$$\longrightarrow T_{\mathbf{b}} = e^{\frac{2\pi i}{M}} = e^{i\mathbf{K}\cdot\mathbf{b}}$$

# Translational symmetry and Bloch's theorem



Suppose the wave is the same after  $N$  translations along  $\mathbf{a}$ , and  $M$  translations along  $\mathbf{b}$ : i.e.  $T_{\mathbf{a}}^N=1$  and  $T_{\mathbf{b}}^M=1$

$$\longrightarrow T_{\mathbf{a}} = e^{\frac{2\pi i}{M}} = e^{i\mathbf{K}\cdot\mathbf{a}}$$

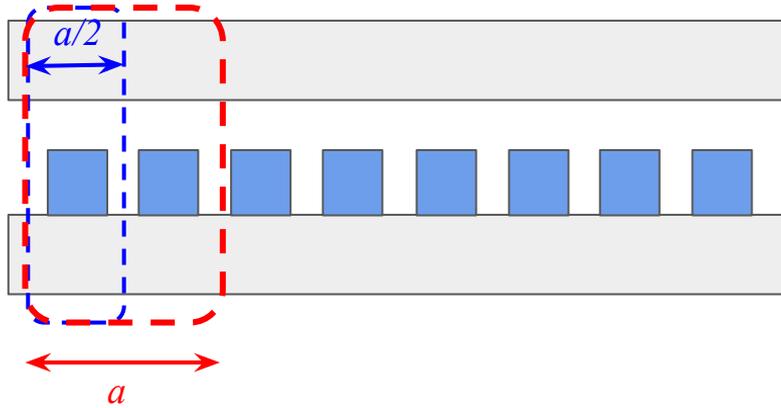
$$\longrightarrow T_{\mathbf{b}} = e^{\frac{2\pi i}{M}} = e^{i\mathbf{K}\cdot\mathbf{b}}$$

This means that the electric field can be written as:

$$E_z(\mathbf{x}) = e^{i\mathbf{K}\cdot\mathbf{x}} u_{\mathbf{K}}(\mathbf{x})$$

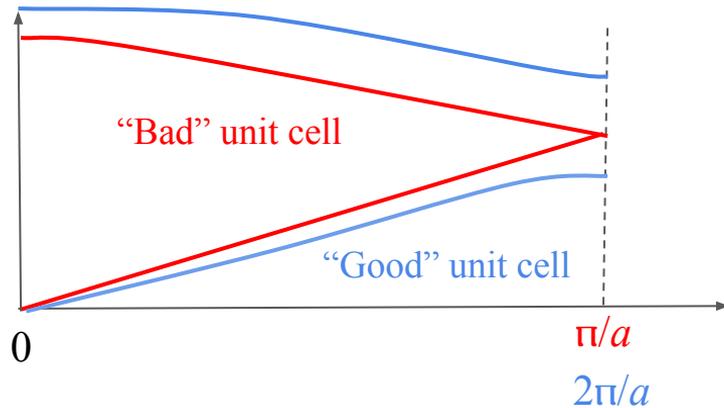
**Bloch's theorem from group theory!**

# Degeneracy in a badly chosen unit cell

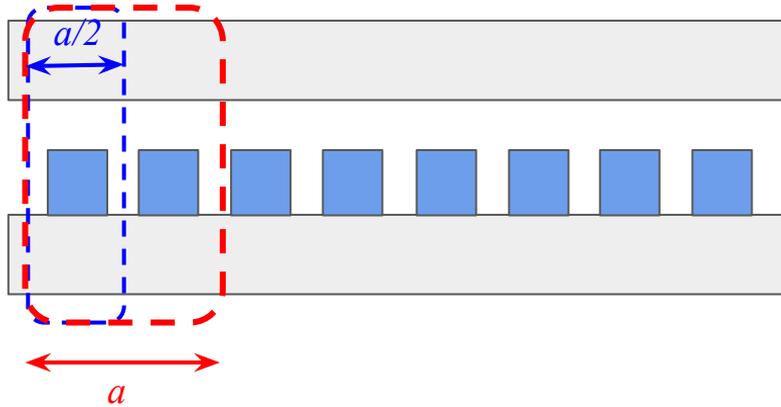


At the Brillouin zone boundary the wave satisfies,

$$E_z(x + a) = -E_z(x)$$



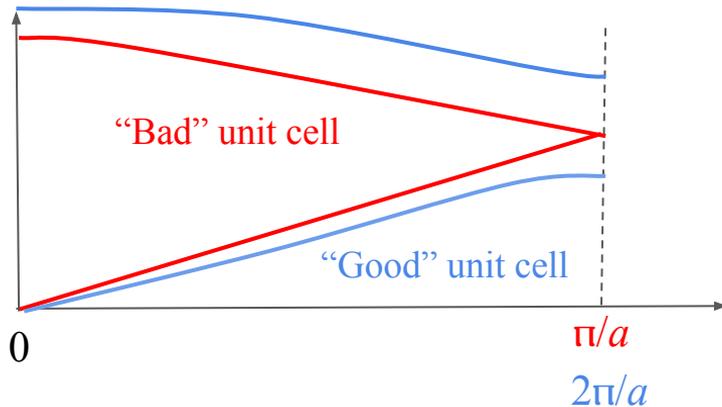
# Degeneracy in a badly chosen unit cell



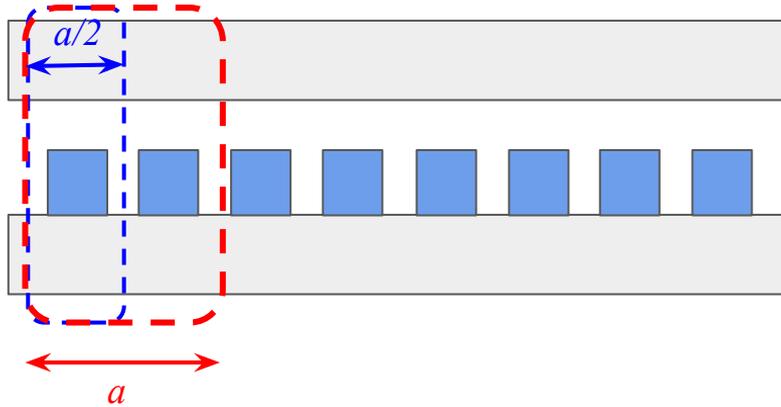
At the Brillouin zone boundary the wave satisfies,

$$E_z(x + a) = -E_z(x)$$

$$\longrightarrow T_{a/2}^2 E_z = -E_z$$



# Degeneracy in a badly chosen unit cell



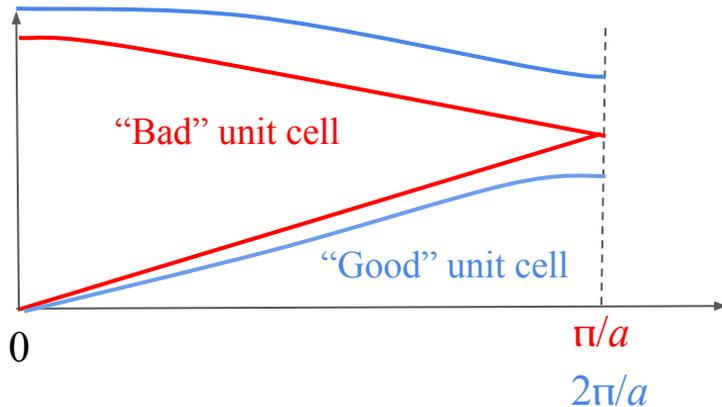
At the Brillouin zone boundary the wave satisfies,

$$E_z(x + a) = -E_z(x)$$

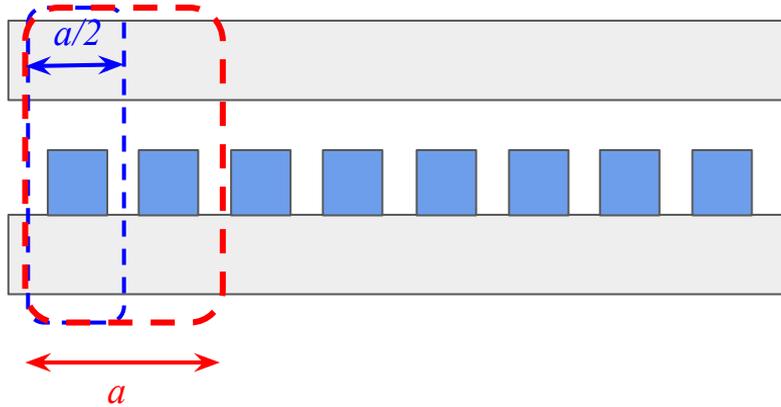
$$T_{a/2}^2 E_z = -E_z$$

At the Brillouin zone boundary we can choose the solution to Maxwell's equations as a real function. Smallest real matrix representation:

$$T_{a/2} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$



# Degeneracy in a badly chosen unit cell



At the Brillouin zone boundary the wave satisfies,

$$E_z(x + a) = -E_z(x)$$

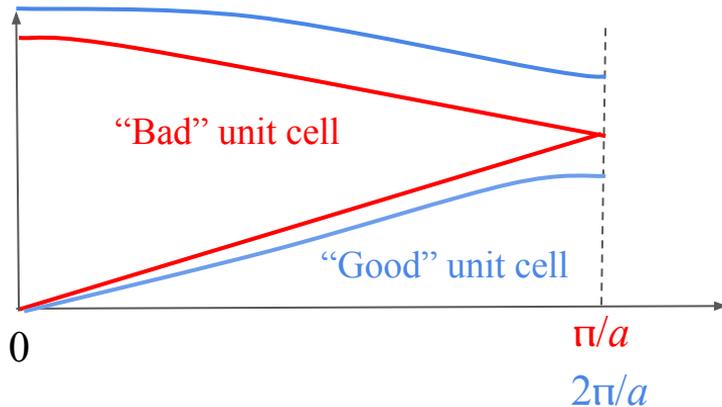
$$T_{a/2}^2 E_z = -E_z$$

At the Brillouin zone boundary we can choose the solution to Maxwell's equations as a real function. Smallest real matrix representation:

$$T_{a/2} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

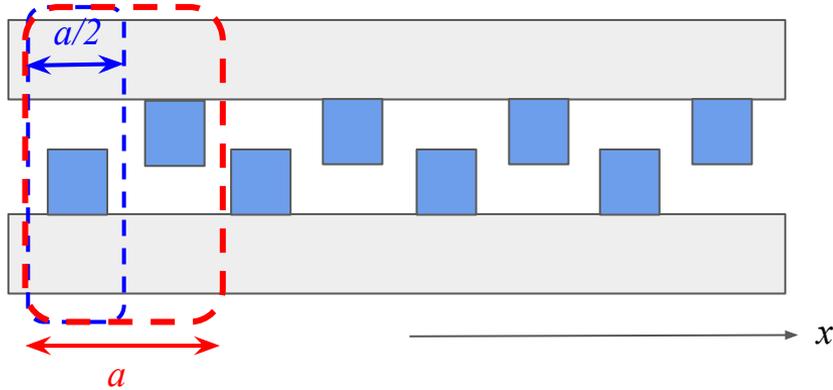
Two dimensional irreducible real representation.

Two bands meet at the Brillouin zone boundary



# Degeneracy from glide and screw symmetry

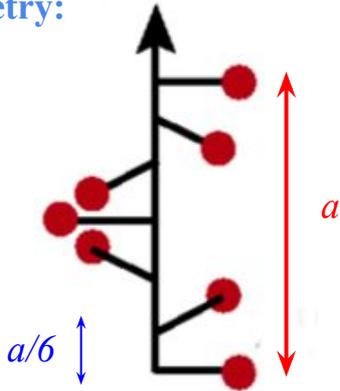
Glide symmetry:



At the Brillouin zone boundary the wave satisfies,

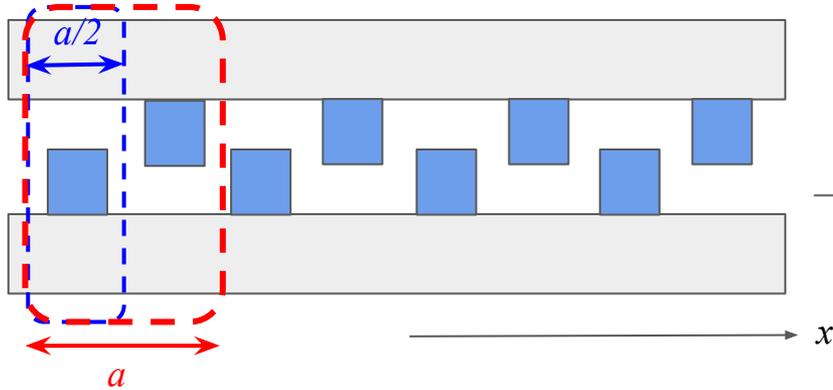
$$E_z(x + a) = -E_z(x)$$

Screw symmetry:



# Degeneracy from glide and screw symmetry

Glide symmetry:

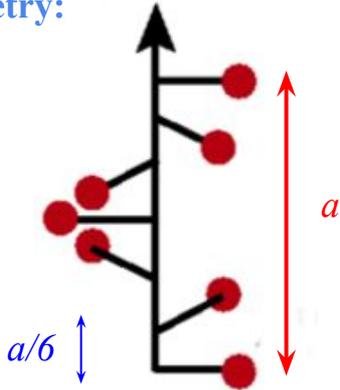


At the Brillouin zone boundary the wave satisfies,

$$E_z(x + a) = -E_z(x)$$

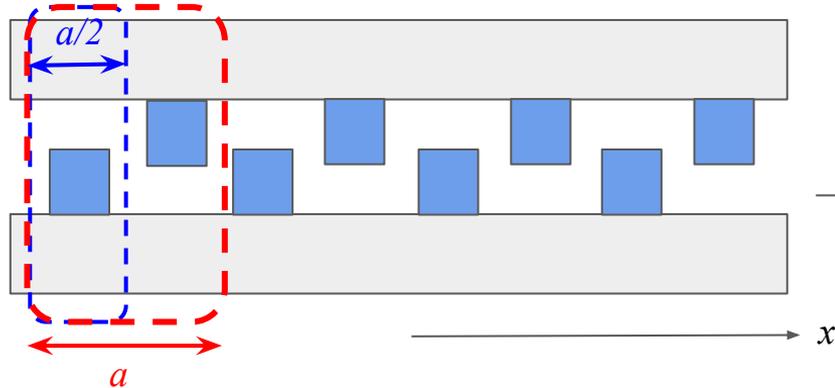
$$(T_{a/N})^N E_z = -E_z \quad (\text{n-fold screw axis})$$

Screw symmetry:

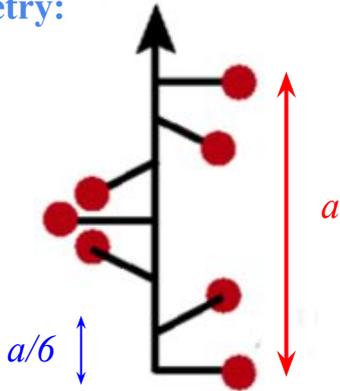


# Degeneracy from glide and screw symmetry

Glide symmetry:



Screw symmetry:



At the Brillouin zone boundary the wave satisfies,

$$E_z(x + a) = -E_z(x)$$

$$(T_{a/N})^N E_z = -E_z \quad (\text{n-fold screw axis})$$

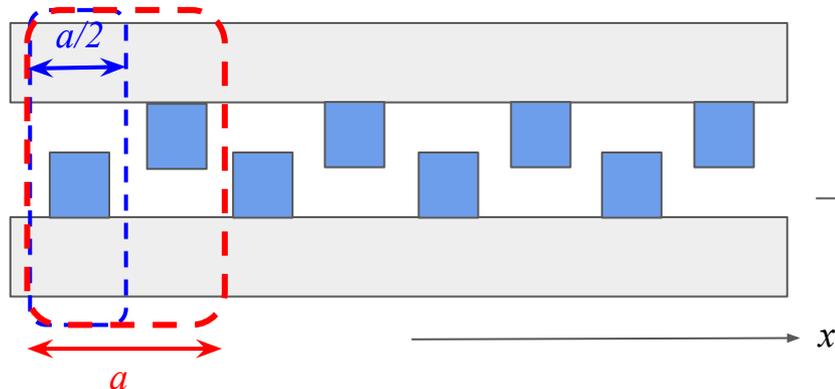
Smallest real matrix representation:

$$T_{a/N} = \begin{pmatrix} \cos(\pi/N) & \sin(\pi/N) \\ -\sin(\pi/N) & \cos(\pi/N) \end{pmatrix}$$

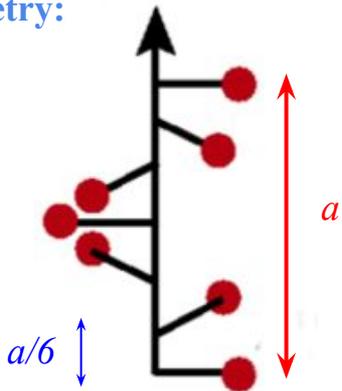
$N=2$  corresponds to glide symmetry transformation

# Degeneracy from glide and screw symmetry

Glide symmetry:



Screw symmetry:



At the Brillouin zone boundary the wave satisfies,

$$E_z(x + a) = -E_z(x)$$

$$(T_{a/N})^N E_z = -E_z \quad (\text{n-fold screw axis})$$

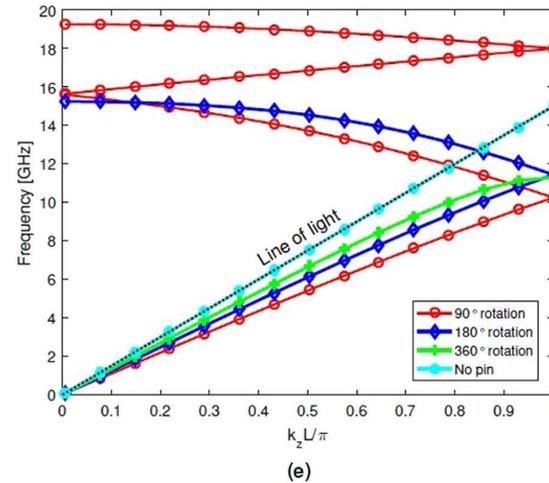
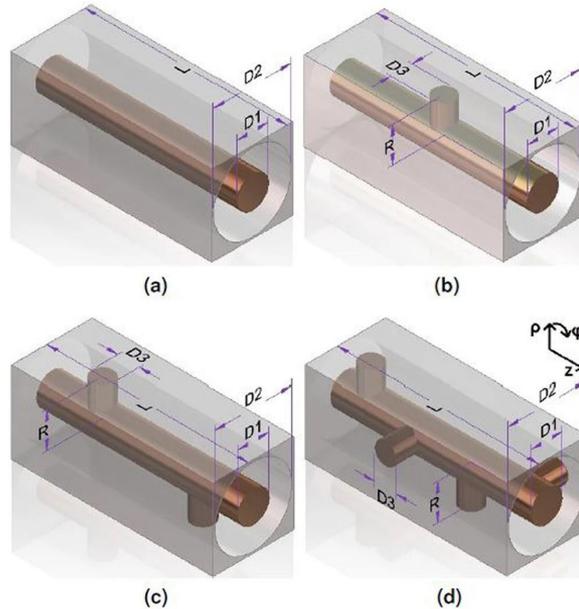
Smallest real matrix representation:

$$T_{a/N} = \begin{pmatrix} \cos(\pi/N) & \sin(\pi/N) \\ -\sin(\pi/N) & \cos(\pi/N) \end{pmatrix}$$

$N=2$  corresponds to glide symmetry transformation

→ **Two bands meet at the Brillouin zone boundary**

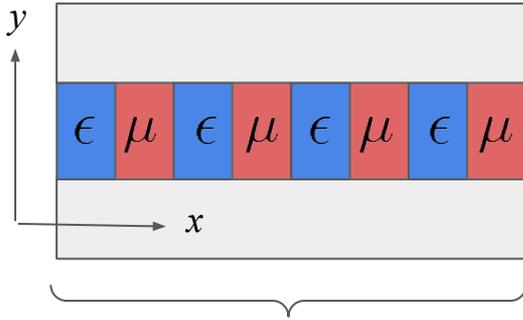
# Degeneracy from glide and screw symmetry



The order of the glide/screw axis makes no difference: always two bands meet.

# Generalized glide/screw symmetry

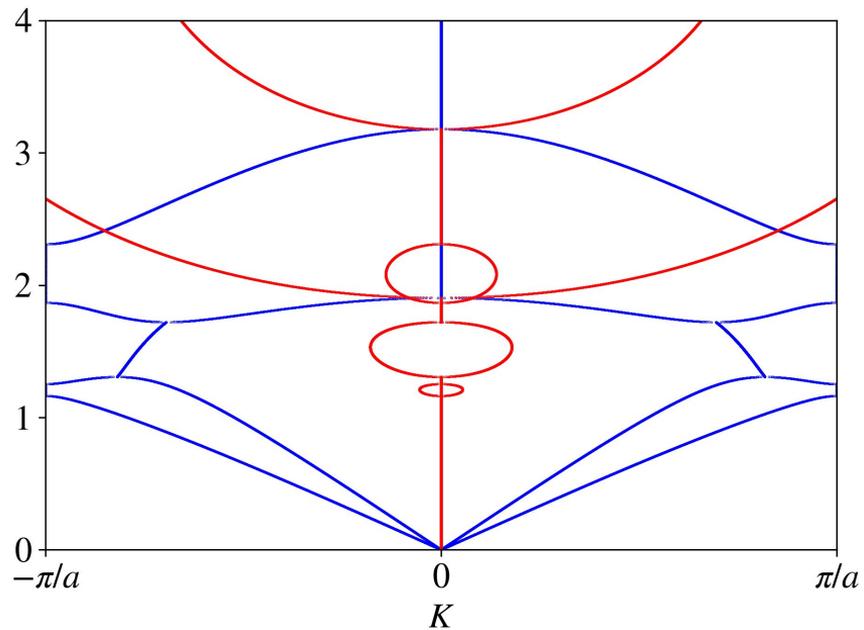
But the symmetry need not be geometrical. We could try other things...**like polarization...**



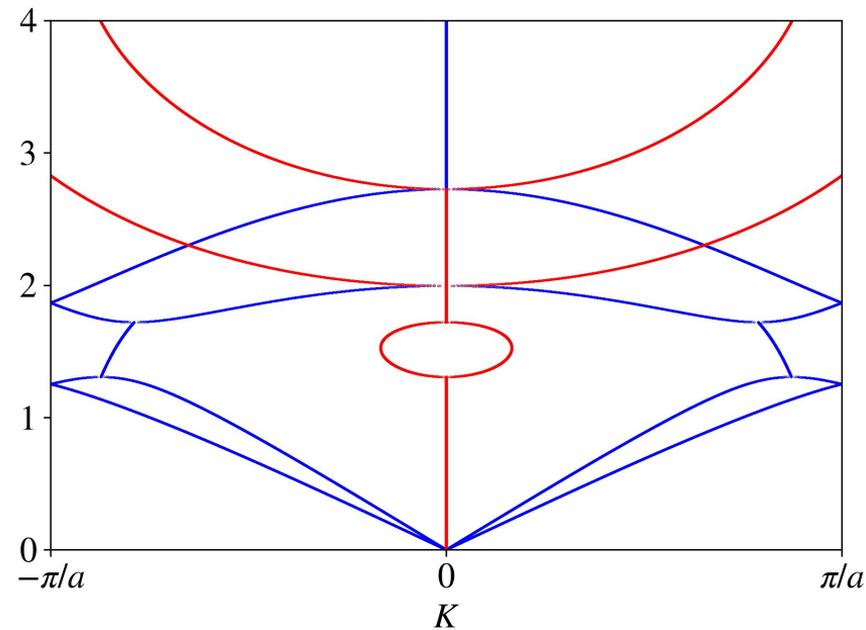
e.g. Alternating anisotropic electric  
and magnetic materials

# Generalized glide/screw symmetry

Without “glide polarization” symmetry



With “glide polarization” symmetry



# Generalized glide/screw symmetry

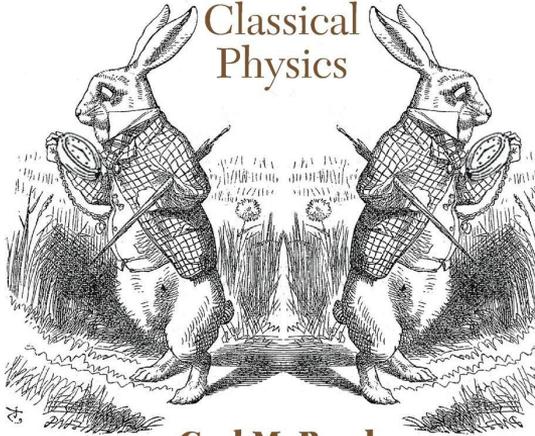


# PT-symmetry (not quite 'glide' symmetry)

## PT Symmetry

in Quantum and

Classical  
Physics



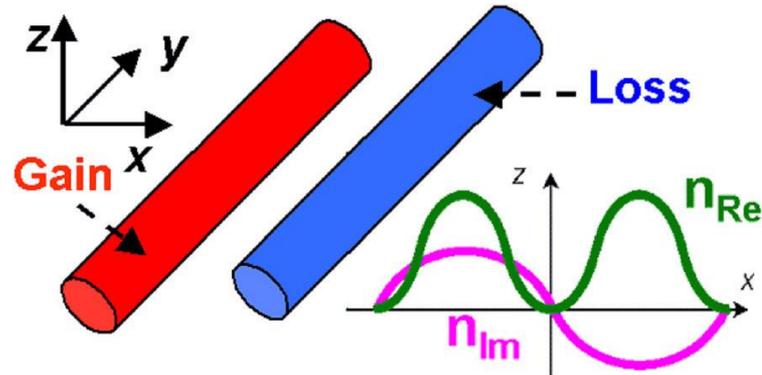
**Carl M. Bender**

*With contributions from*

Patrick E. Dorey, Clare Dunning, Andreas Fring, Daniel W. Hook,  
Hugh F. Jones, Sergii Kuzhel, Géza Lévai, and Roberto Tateo

 World Scientific

Electromagnetic structures need not only have spatial or polarization symmetries. **We can also have symmetries with respect to the direction of time.**

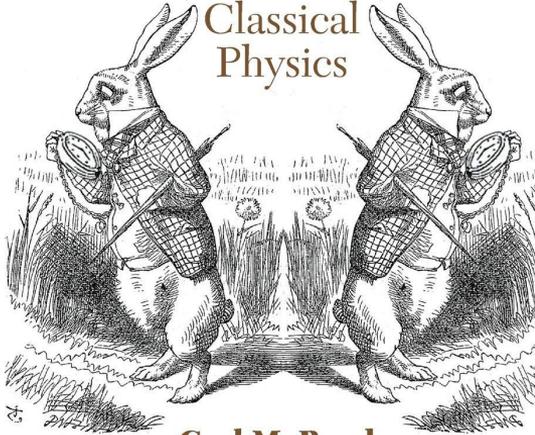


# PT-symmetry (not quite 'glide' symmetry)

## PT Symmetry

in Quantum and

Classical  
Physics



Carl M. Bender

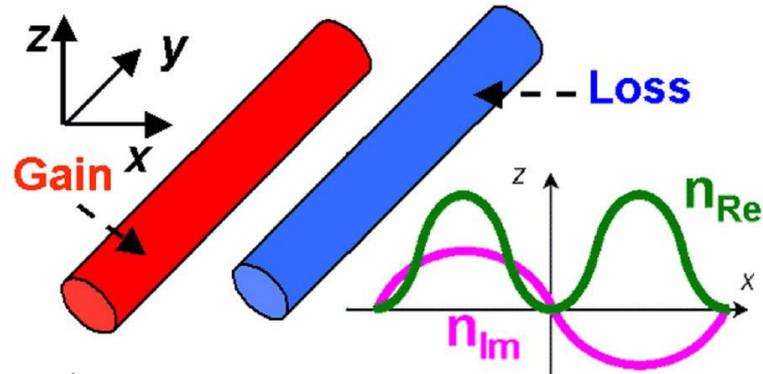
With contributions from

Patrick E. Dorey, Clare Dunning, Andreas Fring, Daniel W. Hook,

Hugh F. Jones, Sergii Kuzhel, Géza Lévai, and Roberto Tateo

 World Scientific

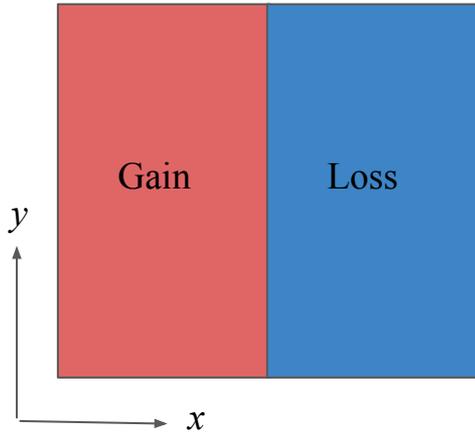
Electromagnetic structures need not only have spatial or polarization symmetries. **We can also have symmetries with respect to the direction of time.**



$$x' = -x$$

$$\epsilon' = \epsilon^*$$

# PT-symmetry (not quite ‘glide’ symmetry)



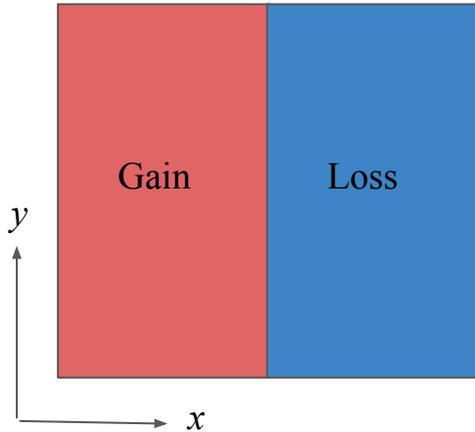
**1D Electromagnetic Helmholtz equation:**

$$\left[ \frac{d^2}{dx^2} + k_0^2 \epsilon(x) - k_z^2 \right] E_z = 0$$

Perform transformation  $x' = -x$ , and complex conjugation

$$k_0 \text{ real: symmetry } E'_z(x) = E_z^*(-x)$$

# PT-symmetry (not quite ‘glide’ symmetry)



**1D Electromagnetic Helmholtz equation:**

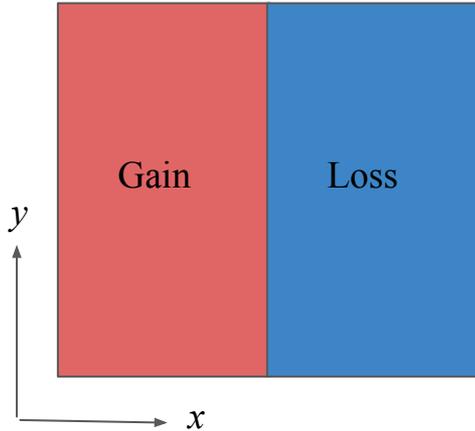
$$\left[ \frac{d^2}{dx^2} + k_0^2 \epsilon(x) - k_z^2 \right] E_z = 0$$

Perform transformation  $x' = -x$ , and complex conjugation

$$k_0 \text{ real: symmetry } E'_z(x) = E_z^*(-x)$$

$$\longrightarrow T_{PT} E_z(x) = E_z^*(-x)$$

# PT-symmetry (not quite ‘glide’ symmetry)



## 1D Electromagnetic Helmholtz equation:

$$\left[ \frac{d^2}{dx^2} + k_0^2 \epsilon(x) - k_z^2 \right] E_z = 0$$

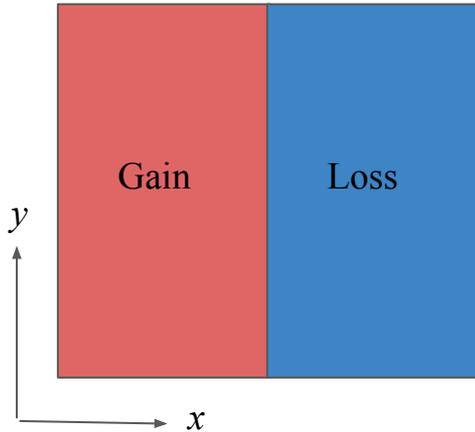
Perform transformation  $x' = -x$ , and complex conjugation

$$k_0 \text{ real: symmetry } E'_z(x) = E_z^*(-x)$$

$$\longrightarrow T_{PT} E_z(x) = E_z^*(-x)$$

$$\longrightarrow T_{PT}^2 = 1$$

# PT-symmetry (not quite 'glide' symmetry)



## 1D Electromagnetic Helmholtz equation:

$$\left[ \frac{d^2}{dx^2} + k_0^2 \epsilon(x) - k_z^2 \right] E_z = 0$$

Perform transformation  $x' = -x$ , and complex conjugation

$$k_0 \text{ real: symmetry } E'_z(x) = E_z^*(-x)$$

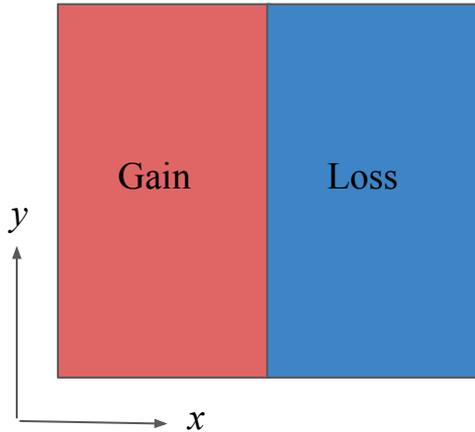
$$\longrightarrow T_{PT} E_z(x) = E_z^*(-x)$$

$$\longrightarrow T_{PT}^2 = 1$$

$$\longrightarrow T_{PT} = \pm 1$$

Very simple 1D irreducible representation!

# PT-symmetry (not quite 'glide' symmetry)



PT-symmetric phase

1D Electromagnetic Helmholtz equation:

$$\left[ \frac{d^2}{dx^2} + k_0^2 \epsilon(x) - k_z^2 \right] E_z = 0$$

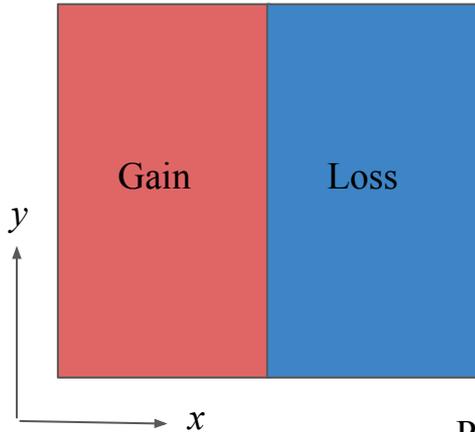
Perform transformation  $x' = -x$ , and complex conjugation

$$\begin{aligned} k_0 \text{ real: symmetry } E'_z(x) &= E_z^*(-x) \\ \longrightarrow T_{PT} E_z(x) &= E_z^*(-x) \\ \longrightarrow T_{PT}^2 &= 1 \\ \longrightarrow T_{PT} &= \pm 1 \end{aligned}$$

Very simple 1D irreducible representation!

$\longrightarrow$  **2 non-degenerate solutions, either even or odd**

# PT-symmetry (not quite ‘glide’ symmetry)



PT-broken phase {  $k_0$  complex:  $E_z(x)$  &  $E_z^*(-x)$  are now solutions to different equations, with frequencies  $k_0$  and  $k_0^*$

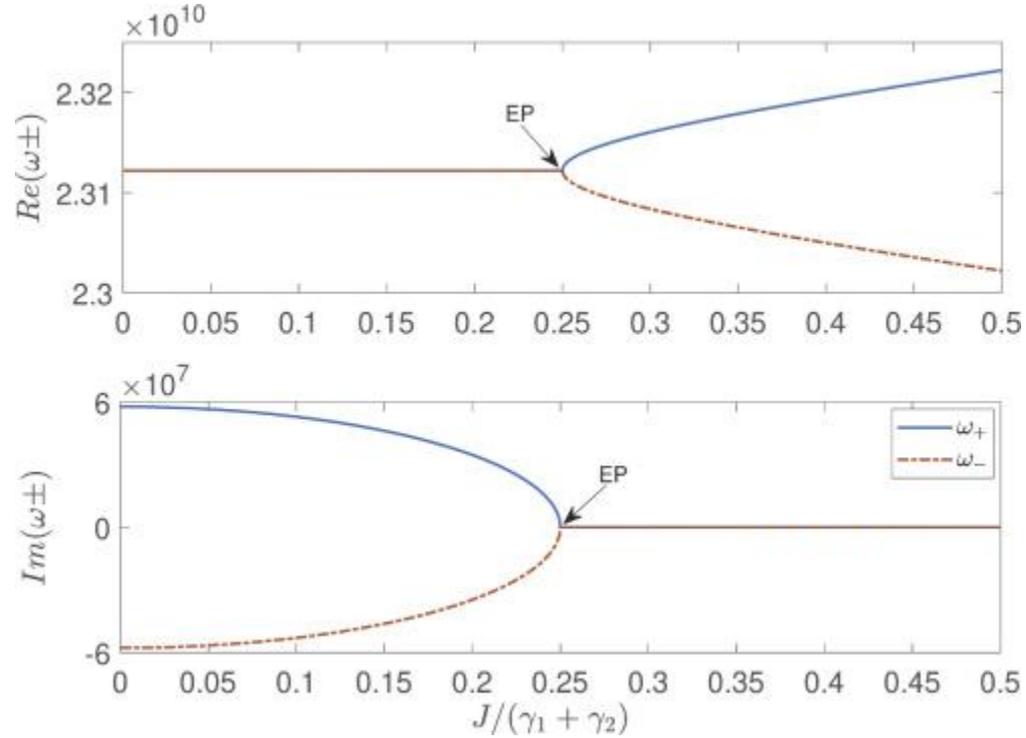
## 1D Electromagnetic Helmholtz equation:

$$\left[ \frac{d^2}{dx^2} + k_0^2 \epsilon(x) - k_z^2 \right] E_z = 0$$

Perform transformation  $x' = -x$ , and complex conjugation

If some parameter (e.g. the scale of the permittivity or wavevector  $k_z$ ) is changed, the PT-symmetric phase can become broken. This is called the *exceptional point*.

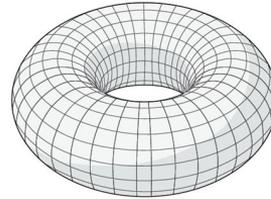
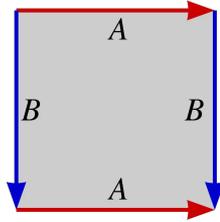
# PT-symmetry (not quite 'glide' symmetry)



# Higher symmetries and topology

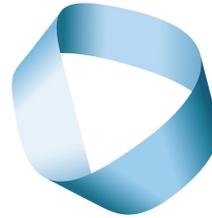
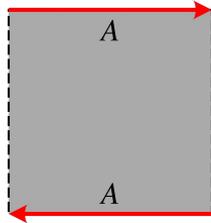
## Visualizing higher symmetries:

Ordinary periodic medium

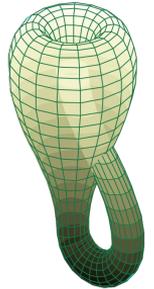
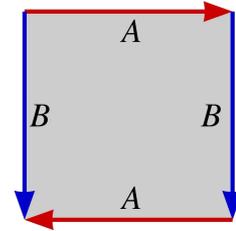


Torus

Higher symmetry along one axis

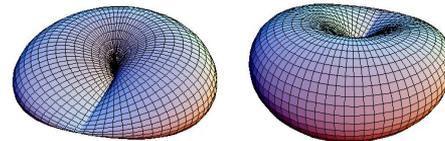
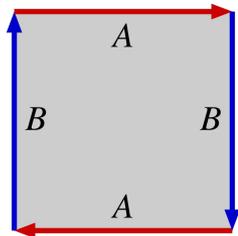


Möbius strip



Klein bottle

Higher symmetry along two axes



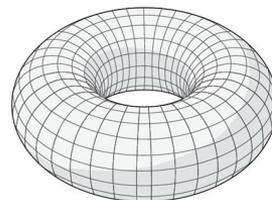
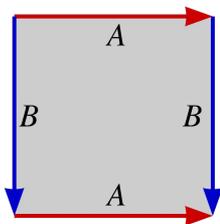
Real projective plane

# Higher symmetries and topology

## Visualizing higher symmetries:

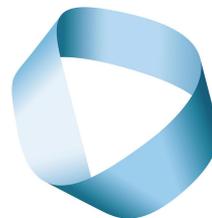
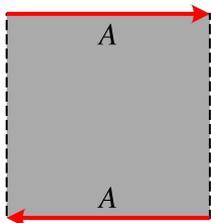
c.f. tomorrow's lecture on topology

Ordinary periodic medium

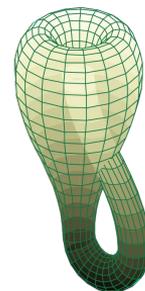
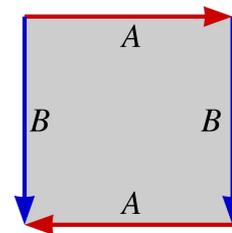


Torus

Higher symmetry along one axis

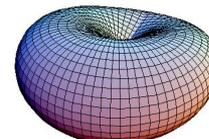
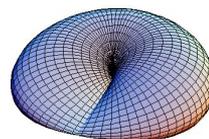
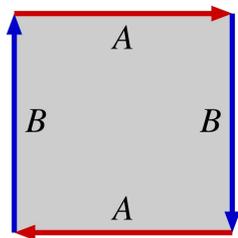


Möbius strip



Klein bottle

Higher symmetry along two axes



Real projective plane

# Summary

- If you are interested in symmetry, **group theory is a useful thing to know!**
- Groups describe symmetries, and their **irreducible representations tell us about the number of resulting degeneracies.**
- There is an important formula relating the number of elements of a group, and the dimensions of the irreducible representations
$$\sum_{\mu} n_{\mu}^2 = g$$
- **We can use group theory to derive Bloch's theorem and degeneracies at the Brillouin zone boundary** in the case of a badly chosen unit cell, glide symmetry, screw symmetry, and generalized glide symmetry.
- There seem to be many possible higher symmetry electromagnetic structures (the analogue of hexagonal ice?). **Group theory is a useful tool to explore this space!**